# Advanced Programming in Quantitative Economics

Introduction, structure, and advanced programming techniques

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## Outline

Steps

Flow

Recap of main concepts

## Day 2 - Morning

#### 9.00L Structuring

- Recursive programming
- Building blocks
- Declarations/data/actions/output
- Revise:
  - Passing data back and forth
- 10.30P Tutorial
  - Addresses
  - Minimal blocks
  - 12.00 Lunch

#### Reprise: What? Why?

Wrong answer:

For the fun of it

A correct answer

To get to the results we need, in a fashion that is controllable, where we are free to implement the newest and greatest, and where we can be 'reasonably' sure of the answers



#### Step 1: Analyse the data

- Read the original data file
- Make a first set of plots, look at it
- Transform as necessary (aggregate, logs, first differences, combine with other data sets)
- Calculate statistics
- Save a file in a convenient format for later analysis



```
savemat("data/fx9709.in7", vDay~mX, {"Date", "UKUS", "EUUS", "JPUS"});
```

### Step 2: Analyse the model

- Can you simulate data from the model?
- Does it look 'similar' to empirical data?
- Is it 'the same' type of input?



### Step 3: Estimate the model

- Take input (either empirical or simulated data)
- Implement model estimation
- Prepare useful outcome



### Step 4: Extract results

- Use estimated model parameters
- Create tables/graphs
- Calculate policy outcome etc.



#### APQE11-2a └─ <sub>Steps</sub>

#### Result of steps

```
main()
{
    decl sData, asIn, vYears, vDay, mRet, vP, vS, dLnPdf, mFilt, ir;
    // Prepare 'magic numbers'
    sData "data/fx9709.in7"; // Or use "data/sim9709.in7";
    asIn= { "UKUS", "EUUS", "JPUS"};
    vYears= <1997, 2009>;
    // Perform analysis, in steps}
Initialise(&vDay, &mRet, sData, asIn, vYears);
    ir= Estimate(&vP, &vS, &dLnPdf, mRet, asIn);
    ExtractResults(&mFilt, vP, vS, mRet);
    Output(vP, vS, mRet, mFilt, ir);
```

- }
- Short main
- Starts off with setting items that might be changed: Only up front in main (*magic numbers*)
- Debug one part at a time!
- Easy for later re-use, if you write clean small blocks of code
- Input to estimation program is *prepared* data file, not raw data.

## Ch 5: Program flow

Last main chapter on low-level Ox language

- Read your program. There is only one route the program will take. You can follow it as well.
- Statements are executed in order, starting at main()
- A statement can call a function: The statements within the function are executed in order, until encountering a return statement or the end of the function
- A statement can be a *looping* or *conditional* statement, repeating or skipping some statements. See below.
- (The order can also be broken by break, continue or goto statements. Don't use, ugly.)

And that is all, any program follows these lines. (Sidenote: Objects etc)

## Flow 2: Reading easily

As a general hint:

Main file:

- #include routines (see later)
- Contains only main()
- Preferably only contains calls to routines (Initialise, Estimate, Output)
- Each routine: Maximum 30 lines / one page. If longer, split!

## All work in functions

All work is done in functions

```
Listing 1: recap1.ox
```

```
#include <oxstd.h>
main()
{
    decl dX, dX2;
    dX= 5.5;
    dX2= dX^2;
    println ("The square of ", dX, " is ", dX2);
}
```

According to the function header

main()

the function main takes no arguments. This function uses only println as a function, rest of the work is done locally. Functions

## Squaring and printing

Use other functions to do your work for you

```
printsquare(const dIn)
{
    decl dIn2;
    dIn2= sqr(dIn);
    println ("The square of ", dIn, " is ", dIn2);
}
main()
{
    decl dX;
    dX= 5.5;
    printsquare(dX);
    printsquare(6.3);
}
```

Here, printsquare does not give a return value, only screen output.

printsquare takes in one argument, with a value locally called dIn. Can either be a true variable (dX), a constant (6.3), or even the outcome of a calculation (dX-5).

#### return

Alternatively, use return to give a value back to the calling function (as e.g. the ones() function also gives a value back).

Listing 2: return.ox

```
#include <oxstd.h>
onesL(const iR, const iC)
{
    decl mX;
    mX= zeros(iR, iC) + 1;
    return mX;
}
main()
{
    decl mX;
    mX= onesL(2, 4);
    print(<u>"Ones matrix, using local function onesL: "</u>, mX);
}
```

Recap of main concepts

Return statement

## Indexing

A matrix consists of multiple doubles, a string of multiple characters, an array of multiple elements. Get to those elements by using indices (starting at 0):

```
index(const mA, const sB, const aC)
Ł
  println ("Element [0][1] of ", mA, "is ", mA[0][1]);
  println ("Elements [0:4] of '", sB, "' are '", sB[0:4], "'");
  println ("Element [4] of '", sB, "' is ASCII number ", sB[4]);
  println ("Element [1] of ", aC, "is '", aC[1], "'");
3
main()
 decl mX, sY, aZ;
 mX = rann(2, 3);
  sY= "Hello world":
  aZ = \{mX, sY, 6.3\};
  index(mX, sY, aZ);
3
Check out how sB[i:i] is a string, and sB[i] the ASCII-number
```

```
representing the letter (65=A, 66=B, ...) _{15/21}
```



## Scope

Each variable has a scope, a part of the program where it is known.

```
printsquare(const dIn)
{
    decl dIn2;
    dIn2= sqr(dIn);
    println ("The square of ", dIn, " is ", dIn2);
}
main()
{
    decl dX;
    printsquare(dX); printsquare(6.3);
}
Descibilition:
```

Possibilities:

- 1. Local declarations decl dX, or decl dIn2: Only known in the present block, until closing parenthesis of the function.
- Function arguments: Local name for argument to function, in order. Compare local name (dIn) to call (dX, 6.3).
- [Later] Global variables static decl s\_vY, s\_mX: Only used in special situations, with great care; these have full scope for the remainder of the file/program.

## Arrays and multiple assignment

#### Not specific to functions are arrays and multiple assignments:

```
Listing 3: multassign.ox
```

```
#include <oxstd.h>
main()
{
    decl aiRC, iR, iC;
    aiRC= {2, 4}; // Create an array with two integers
    [iR, iC]= aiRC; // Assign the two elements of the array
    // Or use a function, assigning the array of returns
    [iR, iC]= SomeFunctionReturningArrayOfSizeTwo();
}
```

Recap of main concepts

└─ Constant arguments

#### Arguments cannot be changed

Arguments to a function *cannot be changed* in a lasting way. After returning from the function, the old value is back.

```
Listing 4: changeme.ox
```

```
#include <oxstd.h>
changemeerror(const dA)
  dA = 5;
changemencerror(dA)
  dA = 5:
3
main()
  decl dX;
  dX = 3;
  changemeerror(dX);
  changemenoerror(dX);
  println ("Result: ", dX);
3
```

#### Before the addresses

If you prefer, stop here for the moment...

Use constant arguments, return values using return statement. Everything could be written this way.

#### Those addresses again...

As I cannot change the argument itself, pass along the (fixed) address of a variable:

```
Listing 5: changemedef.ox

changemedef(const adX)

{

    adX[0]= 7; // Do not change the address, but the value at the address

}

main()

{

    decl dX;

    dX= 3;

    println ("Value before ChangeMeDef: ", dX);

    changemedef(&dX);

    println ("Value after ChangeMeDef: ", dX);

}
```

## Addresses and indexing

Indexing works with one index at a time. If you have the address of an array with a matrix in 3rd place, of which you want to change element [6] [2], just check the indexing carefully.

#### Listing 6: index.ox