# Advanced Programming in Quantitative Economics 

Introduction, structure, and advanced programming techniques

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## Syntax frames

Below a series of frames on syntax in Ox. Read them through, try out in small programs if you understand the meaning.

## Chapter 1: Getting started

## Exercise:

1. Copy the file <ox-home>/samples/myfirst.ox to your personal directory.
2. Open the file in OxEdit (e.g. Windows Explorer, walk there, right mouse button, Send To - OxEdit)
3. Run the program (through Modules - Run - Ox)
(If there is no $\mathrm{O} \times$ option under the Run menu, load the .tool file from the students directory, using Tools -
Add/remove modules - Load from)
Output
```
Ox version 5.10 (Linux_64/MT) (C) J.A. Doornik, 1994-2008
two matrices
    2.0000 0.0000 0.0000
    0.0000 1.0000 0.0000
    0.0000 0.0000 1.0000
    0.0000 0.0000 0.0000
    1.0000 1.0000 1.0000
```


## Using OxEdit

One tab has program
Running the program puts output in separate file/sheet
Errors in code can appear in output file
Workspace indicates opened files


## Type of errors

1. Compilation errors: Like the above, error in the syntax of Ox

Listing 1: myfirst_err.ox

```
print "two matrices", m1, m2);
    // gives compile-time error
```

Ox version 5.10 (Linux_64/MT) (C) J.A. Doornik, 1994-2008
myfirst_err.ox (12): ';' expected but found '<string>'
myfirst_err.ox (12): ';' expected but found ')'
myfirst_err.ox (12): ')' out of place
2. Runtime errors: Impossible computations or commands

Listing 2: myfirst_err.ox

```
print ("product of two matrices", m1 * m2);
    // gives run-time error
Ox version 5.10 (Linux_64/MT) (C) J.A. Doornik, 1994-2008
Runtime error: 'matrix[3][3] * matrix [2][3]' bad operand
Runtime error occurred in main(14), call trace:
myfirst_err.ox (14): main
```

One error can lead to multiple messages: Start solving first in list.

## Chapter 2: Syntax - Comments

```
/* This is standard comment,
    which /* may be nested */.
*/
decl x; // declare the variable x
```

Use them well, use them extensively, use them consistently

```
/*
olsc(const mY, const mX, const amB)
Purpose:
    Performs OLS, expecting the data in columns.
Inputs:
    mY iT x iN matrix of regressors }
    mX iT x iK matrix of explanatory variables X
Outputs:
    amB address of iK x iN matrix with iN sets of OLS coefficients
Return value:
    integer, 1: success, 2: rescaling advised,
                        -1: X'X is singular, -2: combines 2 and -1.
Example:
    ir =olsc(mY, mX, छmmB);
Last changed
    21-04-96 (Marius Doms): made documentation
    06-08-09 (Charles Bos): adapted documentation
```

Use explanation, consistently, before every function, detailing name, purpose, inputs, outputs, return value (and possibly date, author, once per file)

## Program layout

A minimal complete program is:
Listing 3: oxtut2b.ox

```
#include <oxstd.h>
main()
{
    println("Hello world");
}
```

Contains:

1. Include statement, to define all standard functions in Ox ; between $<$ and $>$ to indicate oxstd.h is an intrinsic part of Ox
2. One function header, called main, taking no arguments ()
3. Function body for main(), enclosed in \{\}, with a println statement
Note: Syntax terribly similar to C or Java.

## Statements

## Listing 4: oxtut2c-hun.ox

```
#include <oxstd.h>
main()
{
    decl iN, dSigma, mX, vBeta, vEps;
    iN = 4;
    dSigma = 0.25;
    mX = 1 ~ ranu(iN, 2);
    vBeta = <1; 2; 3>;
    vEps = dSigma * rann(iN, 1);
    print("x", mX, "beta", vBeta, "epsilon", vEps);
}
```

(note: Stick to Hungarian, don't follow the Introduction to $O x$ literally here)

- Declaration: Automatic typing
- Assignment: Integer, double, matrix-function, matrix-constant, function result.
- Print statement


## Identifiers

Identifiers: All names of variables, constants and functions

1. Case sensitive
2. Distinct between blocks of the program; local declaration can overrule global declaration
3. Contain $[A-Z],[a-z],[0-9],[-]$, and start with a letter.
4. Do use sensible names; use Hungarian notation for your own sake

- <1, 2, 3> creates a row vector
- $\langle 1.1 ; 2.2 ; 3.3\rangle$ creates a column vector
- <0, 1, 2; 3, 4, 5> creates a $2 \times 3$ matrix
- <1:4> is the same matrix as <1, 2, 3, 4>
- You cannot combine a matrix constant with a variable: <1, 2, dSigma> leads to a compilation error


## Matrix creation

- Assign a matrix constant $m \mathrm{X}=<1,2>$;
- Assign another matrix or function of matrices $m X=m Y+m Z$;
- Assign the result of a standard function, $m X=$ unit(2); mY= zeros(2, 6); mZ= range(0, 1, .05);
- Concatenate other elements $m X=1 \sim m Y$; $m Z=m X|m Y, m Y=(0 \sim 1)|\left(2^{\sim} 3\right)$;
Check that the matrices 'fit' when you concatenate or sum.
Scalars fit everywhere.
Warning: Concatenating matrices is (relatively) slow, don't do it within a loop. Compare:

```
    Listing 5: inefficient
mX= <>;
for (i= 0; i < 1000; ++i)
    // Concatenate random numbers
    mXI= rann (1, 5);

Listing 6: efficient
```

mX= zeros(1000, 5);

```
mX= zeros(1000, 5);
for (i= 0; i < 1000; ++i)
for (i= 0; i < 1000; ++i)
    // Place random numbers
    // Place random numbers
    mX[i][]= rann(1, 5);
```

```
    mX[i][]= rann(1, 5);
```

```

\section*{Simple functions}

The most simple Ox function has no arguments, and returns no value. The syntax is:
function_name ()
\{
statements
\}
For example:
Listing 7: func-sometext.ox
```

\#include <oxstd.h>
sometext()
{
print("Some text\n");
}
main()
{
sometext();
}

```

\section*{Function arguments}
- Each function can take one or more arguments.
- [Each argument can be declared const, or non-constant. For non-constant arguments, Ox copies the value of the argument internally, and hence it is slower than using const arguments.]
- Always declare your arguments to be const.
- (The last argument may be a set of three dots, ..., indicate a variable number of arguments. Advanced)

Listing 8: oxtut2d.ox
```

\#include <oxstd.h>
dimensions(const mX)
{
println("the argument has "",
}
main()
{
dimensions( zeros(40, 5) );
}

```

\section*{Forward function declarations (usg...)}

Ox can use a function only when it is known, or at least when the calling sequence is known. Hence either
1. Put the functions before the main() routine
2. Put the function after the main() routine, and use a forward declaration, putting the function heading with a semicolon up front.
```

MyOls(const mY, const mX); // forward declaration
main()
{
// Now MyOls may be used here
}
MyOls(const mY, const mX)
{
// Specification of MyOls
}

```

The header files (e.g. oxstd.h) mainly list all the function declarations together, whereas the source code resides elsewhere.

\section*{Returning a value}

The syntax of the return statement is:
return return_value ;
Or, to exit from a function without a return value:
return;
You may exit from a function at the end, or also at an earlier stage; remaining commands are not executed.
If you exit at the end, and do not want to return anything, return statement is not needed.

\section*{Multiple returns}

Multiple values can be returned as an array:
```

func()
{
return { mA, sB, vC };
}

```
which can then be assigned as follows:
```

[mX, sY, vZ] = func();

```

Note how the names within the routine should match, and the names outside the routine (e.g. in the main() routine) should match; what is called \(m \mathrm{X}\) in main() can be called mA in func.

\section*{Returning values through arguments}

Quite often more convenient to call a routine such that an argument can get changed, e.g.
```

ir= MyOlsc(vY, mX, \&vBeta);

```
- This call passes an address of vBeta to MyOlsc
- The address itself is not changed in MyOlsc
- Only what is at the address [color of building], is changed
```

                                    Listing 9: myolsc.ox
    MyOlsc(const vY, const mX, const avBeta)
{
// Adapt the value at the address avBeta, its first array value
avBeta[0]= invertsym(mX'mX)*mX'vY;
return 1;
}

```

\section*{APQE11-Syntax}
\(L_{\text {Getting started }}\)

\section*{Checking arguments}

\section*{Listing 10: oxtut2g_hun.ox}
```

\#include <oxstd.h>
test1(iX) // no const, because x will be changed
{
iX = 1;
println("in test1: x=", iX);
}
test2(const aiX)
{
// Change value AT address, not the address itself
aiX[0] = 2;
println("in test2: x=", aiX[0]);
}
main()
{
decl iX = 10;
println("x = ", iX);
test1(iX); // pass x
println("x = ", iX);
test2(\&iX); // pass address of }
println("x = ", iX);
}

```

\section*{Indexing}

All items with multiple components can be indexed.
Note that indexing starts at 0 , as in \(C / C++\)
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- \(m X[: 2][]\) : The first three rows of the matrix
- mX[miI] [miJ]: Advanced: The cross-section of rows with indices in miI and columns with indices in miJ are given.

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- avX[2]: Element 3 of an array; according to the Hungarian notation of the name, this seems to be a vector.
- amX [2] [0] [1]: Element in the first row, second column, of the matrix at element 3 of the array. Matrices are 2-dimensional, further dimensions implemented as arrays.

\section*{Operators}
\begin{tabular}{clcccc}
\hline operator & operation & & & \\
\hline ' & transpose, & \(m \times n\) & \(m \times k\) & \(n \times k\) & \(A^{\prime} b\) \\
\(\sim\) & (matrix) power & \(m \times m\) & \(1 \times 1\) & \(m \times m\) & \(A^{b}\) \\
\(*\) & (matrix) multiplication & \(n \times k\) & \(k \times m\) & \(n \times k\) & \(A B\) \\
\(/\) & (matrix) division & \(m \times n\) & \(p \times n\) & \(p \times m\) & \(A B^{-1}\) \\
\(* *\) & (matrix) Kronecker product & \(m \times n\) & \(p \times q\) & \(m p \times n q\) & \(a_{i j} B\) \\
+ & addition & \(m \times n\) & \(m \times n\) & \(m \times n\) & \(A+B\) \\
- & subtraction & \(m \times n\) & \(m \times n\) & \(m \times n\) & \(A-B\) \\
\(\sim\) & horizontal concatenation & \(m \times n\) & \(m \times k\) & \(m \times n+k\) & {\([A B]\)} \\
I & vertical concatenation & \(m \times n\) & \(k \times n\) & \(m+k \times n\) & {\([A ; B]\)} \\
\hline.\(^{\sim}\) & element-by-element power & \(m \times n\) & \(1 \times 1\) & \(m \times n\) & \(a_{i j}^{b}\) \\
.\(*\) & element-by-element multiplication & \(m \times n\) & \(m \times n\) & \(m \times n\) & \(a_{i j} b_{i j}\) \\
.\(/\) & element-by-element division & \(m \times n\) & \(m \times n\) & \(m \times n\) & \(a_{i j} / b_{i j}\) \\
\hline \hline
\end{tabular}

\section*{Operators: Special cases}
- A scalar combines with everything. Correct is 1 mX (concatenate a vector of ones with mX ), incorrect is \(\langle 1\rangle \mathrm{mX}\) (unless mX has one row; it results in a warning that the matrix is padded with zeros to make things fit).
- Adding (or subtracting) a row and column vector is correct:
\[
\left(\begin{array}{ll}
x_{0} & x_{1}
\end{array}\right)+\left(\begin{array}{l}
y_{0} \\
y_{1} \\
y_{2}
\end{array}\right)=\left(\begin{array}{ll}
x_{0}+y_{0} & x_{1}+y_{0} \\
x_{0}+y_{1} & x_{1}+y_{1} \\
x_{0}+y_{2} & x_{1}+y_{2}
\end{array}\right) .
\]

\section*{Relational and logical operators}

Comparison can be done in two ways
- Using the standard operators: Results in one, scalar, outcome, either TRUE \(\equiv 1\) or FALSE \(\equiv 0\). Note that e.g. \(\mathrm{mX}>\mathrm{mY}\) is true only when all elements of \(m \mathrm{X}\) are larger than the corresponding elements of mY
- Dot-version: Using element-by-element operators results in a matrix filled with 0's and 1's.


\section*{Comments on operators}

\section*{Question}

If \((\mathrm{mX}<\mathrm{mY})=\) FALSE, then what is the outcome of the comparison ( \(\mathrm{mX}>=\mathrm{mY}\) )?

\section*{Boolean shortcut}

If an expression involves several logical operators after each other, evaluation will stop as soon as the final result is known. For example in (1 || checkval (mX)) the function checkval is never called, because the result will be true regardless of its outcome. This is called a boolean shortcut.

\section*{Assignments and combinations}

Assignment is also an operator, i.e., an assignment 'leaves a value' which can be used in further assignments:
```

decl x1, x2, x3, x4;
x1= 0; x2= 0; x3= 0; x4= 0;
// or more concisely
x1= x2= x3= x4= 0;

```

Some others:
```

x1+= 2;
x4/= (x1+x2);
x2-= x1;
x1~= x2;
x3*= 5;
x4|= x3;
++x 1;
x1++;
--x2;
x2++;

```

\section*{Quiz-question: 5-minute exercise}

Check in a small program the difference between ++x1 and x1++.

Who is the first to find it?

\section*{Conditional assignment}

Advanced, but useful shortcut
Listing 11: oxcond.ox
```

if (dX > 0)
dY = 1;
else
dY = -1;
// is equivalent to
dY= (dX > 0) ? 1 : -1;

```

Can also be done element-by-element, i.e.
\(\mathrm{mY}=(\mathrm{mX} .>0)\) ? \(1 . . \quad-1\);
would create a matrix \(m Y\) of the same size of \(m X\), containing \(1,-1\) according to the sign of mX .
Very useful in creating dummies, think of probit models.

\section*{Combining assignments: Comma operator (usgy...)}

One statement runs from a ; to the next ;
One statement may contain multiple assignments, split by the comma operator:
\(i=1, k=2\);
You might just as well put
\(\mathrm{i}=1\); \(\mathrm{k}=2\);
in most situations; using the comma operator is ugly in most situations. A possible exception is in the initialisation of a for-loop:
```

decl i, k;
for (i= 0, k= 1; i < 5; i += 2)
print ("i= ", i, " k= ", k);
// Easier to read is the following
k= 1;
for (i= 0; i < 5; i += 2)
print ("i= ", i, " k= ", k);

```

\section*{Operator precedence}

See table 3.1 in the introduction, of the web-page on your computer.
Be careful at first, use parentheses to make sure.

\section*{For-loops}

At a later stage, we discuss looping constructs in more detail. For the exercise, you need the for-loop.
Syntax:
```

for (init_expr; test_expr ; increment_expr)
statement

```

Steps in the for-loop are
1. Initialise, executing the init_expr
2. If the test_expr is true
2.1 execute the statement,
2.2 execute the increment_expr, and go to 2 .
3. Continue with first statement after the loop.

The statement can either be a singular statement, e.g.
\[
d X=\operatorname{rann}(1,5) ;
\]
or a compound statement, blocking together a group of statements within curly parentheses \{ \}.

\section*{Example for-loop}

Listing 12: oxforloop.ox
```

k= 1;

```
for ( \(i=0 ; i<5 ;++i)\)
    \{
        \(\mathrm{k} *=2\);
        println (" \(i=\) ", \(i, \quad " k=\) ", \(k)\);
    \}

What would be the output?

\section*{Loop: For}

See earlier frames. More extensive example
Listing 13: oxforloop_ext.ox
```

\#include <oxstd.h>
main()
{
decl i, k;
for (i= 0, k= 1; (i < 5) \&\& (k < 7); ++i, k*= 2)
println (" i= ", i, " k= ", k);
}

```

The initialisation and increment statements can be split into many segments separated by comma's; the test statement can be a compounded test.
For your own sake: Don't follow the example, keep the loop simple, e.g. use a while-loop instead.

\section*{Loop: While}

\section*{Listing 14: oxforloop_ext.ox}
```

println ("With a while-loop");
i= 0; k= 1;
while ((i < 5) \&\& (k < 7))
{
println ("M= ", i, " k= ", k);
++i;
k*= 2;
}

```
or, to run the loop at least once:
Listing 15: oxforloop_ext.ox
```

println ("With a do-while-loop");
i= 0; k= 1;
do
{
println ("i= ", i, " k= ", k);
++i;
k*= 2;
}
while ((i < 5) \&\& (k < 7));

```

\section*{Conditional statements: If}
```

if ( condition )
statement
else if ( condition )
statement
else
statement

```

A condition evaluating to a non-zero value is considered true. For a matrix, only if the full matrix is FALSE (i.e. 0), then the result is considered FALSE. Any non-zero element makes it true.
Note that FALSE \(=0\), TRUE \(=1\), and true is any non-zero value

\section*{Conditional statements: Case}

Alternative way, if you know what values i can take on:
Listing 16: oxswitch.ox
```

switch_single (i)
{
case 0:
println ("zero"); // Single statement
case 1:
{
println ("one"); // Single compound statement
println ("So I said, one...");
}
default:
println ("something else");
}

```

\section*{Conditional statements: Assignment}

Also possible:
\(A=\) Condition .? Value if true .: Value if false

Listing 17: oxcond.ox
```

dY= (dX > 0) ? 1 : -1;

```
\(\mathrm{mY}=(\mathrm{mX} .>0) . ? 1\).: -1 ; Multiple elements at once

Very useful in creating dummies, think of probit models.

\section*{Further topics: NaN}

Not a Number, or NaN for short is the missing value which is supported by computer hardware.
- Use . NaN to represent the missing value in Ox code.
- In a matrix constant, you may use a dot to represent a NaN .
- Or use the predefined constant M_NAN (defined in oxfloat.h).
- The format used when printing output is NaN .
```

\#include <oxfloat.h> // defines M_NAN
main()
{
decl mX, d1, d2;
mX = < . > ; d1 = .NaN; d2 = M_NAN;
print(mX + 1, d1 == .NaN, " "', d2 / 2);
}

```

Any computation involving a NaN results in a NaN , so in this example \(\mathrm{d} 2 / 2\) is also. NaN . Comparison is allowed and \(\mathrm{d} 1==\) . NaN evaluates to one (so is TRUE).
Preferably use ismissing(d1) or isdotmissing(mX) instead.

\section*{Further topics: NaN II}

Functions operating with missings:
- deleter (mX): deletes all rows which have a NaN ,
- selectr (mX): selects all rows which have a NaN ,
- isdotnan \((\mathrm{mX})\) : returns matrix of 0 's and 1 's: 1 if the element is a \(\mathrm{NaN}, 0\) otherwise,
- isnan(mX): returns 1 if any element is a \(\mathrm{NaN}, 0\) otherwise.
- isdotmissing (mX): returns matrix of 0's and 1's: 1 if the element is a NaN or \(\pm\) infinity, i.e. M_NAN, M_INF or M_INF_NEG, 0 otherwise.
- ismissing (mX): returns 1 if any element is a NaN or \(\pm\) infinity, i.e. M_NAN, M_INF or M_INF_NEG, 0 otherwise.

\section*{Some constants}

Using \#include <oxfloat.h> delivers the constants
\begin{tabular}{ll} 
M_PI & \(\pi\) \\
M_2PI & \(2 \pi\) \\
M_PI_2 & \(\pi / 2\) \\
M_1_PI & \(1 / \pi\) \\
M_SQRT2PI & \(\sqrt{2 \pi}\) \\
M_NAN & Missing, test using isnan/ismissing \\
M_INF & \(\infty\), test using isdotinf/ismissing \\
M_INF_NEG & \(-\infty\), test using isdotinf/ismissing
\end{tabular}

To exit Ox before reaching the end of the program, use
```

exit(iErr);

```
where iErr is an integer, the exit code Ox will return to the operating system.

\section*{Further topics: Scope}

Any variable is available only within the block in which it is declared.
```

static decl s_vY; // Available throughout this file
fnPrint(const mX)
{
decl vY; // Only available in fnPrint() block
vY= 4;
print ("vY: ", vY, ", Static s_vY: ", s_vY, ", mX: ", mX);
}
main()
{
decl vY; // Only available in main() block
vY= 6;
s_vY= 2; // Filll global variable
fnPrint(vY);
}

```

Use static variables only when absolutely needed; there are cases where we cannot escape it.
Note: Ugly, confusing, incorrect use of Hungarian notation (where?)!```

